Knowing a, we can predict through Eq. (28) a definite scaling law binding on the iterates of any scheme possessing period doubling. The law has, indeed, been amply verified experimentally. By Eq. (29), we see that the relevant operation upon functions that underlies period doubling is functional composition followed by magnification, where the magnification is determined by the fixed-point condition of Eq. (29) with the function g the fixed point in this space of functions. However, Eq. (29) does not describe a stable fixed point because we have not incorporated in it the parameter increase from λ_n to λ_{n+1} . Thus, g is not the limiting function of the curves in the circulation squares, although it is intimately related to that function. The full theory is described in the next section. Here we merely state that we can determine the limiting function and thereby can determine the location of the actual elements of limiting 2ⁿ-cycles. We also have established that g is an unstable fixed point of functional composition, where the rate of divergence away from g is precisely δ of Eq. (3) and so is computable. Accordingly, there is a full theory that determines, in a precise quantitative way, the aperiodic limit of functional iterations with an unspecified function f.

Some Details of the Full Theory

Returning to Eq. (28), we are in a position to describe theoretically the universal scaling of high-order cycles and the convergence to a universal limit. Since d_n is the distance between $x = \frac{1}{2}$ and the element of the 2^n -cycle at λ_n nearest to $x = \frac{1}{2}$ and since this nearest element is the 2^{n-1} iterate of $x = \frac{1}{2}$ (which is true because these two points were coincident before the n^{th} period doubling began to split them apart), we have

$$d_{n} = f^{2n-1}(\lambda_{n}, \frac{1}{2}) - \frac{1}{2}.$$
 (32)

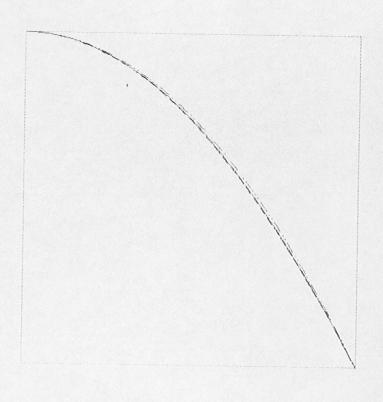


Fig. 8. The superposition of the suitably magnified dotted squares of $f^{2^{n-1}}$ at λ_n (as in Figs. 5a, 7a, ...).

For future work it is expedient to perform a coordinate translation that moves $x = \frac{1}{2}$ to x = 0. Thus, Eq. (32) becomes

$$d_n = f^{2^{n-1}}(\lambda_n, 0)$$
. (33)

Equation (28) now determines that the rescaled distances,

$$r_n \, \equiv \, (-\alpha)^n \, \, d_{n+1} \, \, . \label{eq:rn}$$

will converge to a definite finite value as $n \to \infty$. That is,

$$\lim_{n\to\infty} (-\alpha)^n f^{2^n}(\lambda_{n+1},0) \tag{34}$$

must exist if Eq. (28) holds.

However, from Fig. 8 we know something stronger than Eq. (34). When the nth iterated function is *magnified* by $(-\alpha)^n$, it converges to a definite function. Equation (34) is the value of this function at x = 0. After the magnification, the convergent functions are given by

$$(-\alpha)^n f^{2^n} \ (\lambda_{n+1}, x/(-\alpha)^n)$$
 .

Thus,

$$g_1(x) \equiv \lim_{\substack{n \to \infty \\ n \to \infty}} (-\alpha)^n f^{2n}(\lambda_{n+1}, x/(-\alpha)^n) \quad (35)$$

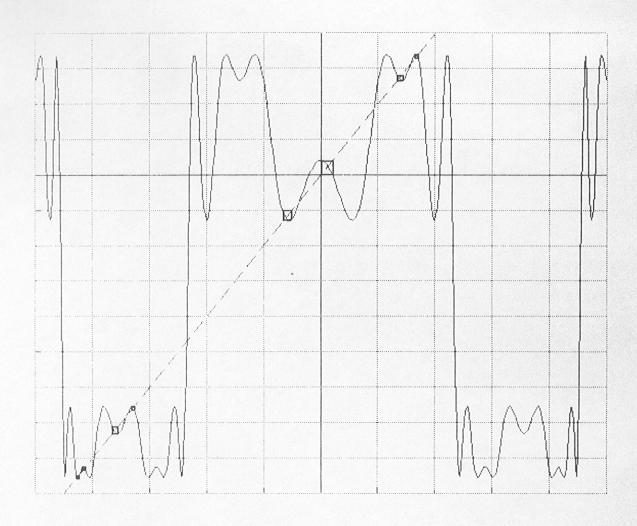


Fig. 9. The function g₁. The squares locate cycle elements.

is the limiting function inscribed in the square of Fig. 8. The function $g_1(x)$ is, by the argument of the restriction of f to increasingly small intervals about its maximum, the *universal* limit of all iterates of all f's with a quadratic extremum. Indeed, it is numerically easy to ascertain that g_1 of Eq. (35) is always the same function independent of the f in Eq. (32).

What is this universal function good for? Figure 5a shows a crude approximation of g_1 [n = 0 in the limit of Eq. (35)], while Fig. 7a shows a better approximation (n = 1). In fact, the extrema of g_1 near the fixed points of g_1 support circulation squares each of which contains two points of the cycle. (The two squares shown in Fig. 7a locate the four elements of the cycle.) That is, g_1 determines the location of elements of high-

order 2^n -cycles near x = 0. Since g_1 is universal, we now have the amazing result that the location of the actual elements of highly doubled cycles is universal! The reader might guess this is a very powerful result. Figure 9 shows g_1 out to x sufficiently large to have 8 circulation squares, and hence locates the 15 elements of a 2^n -cycle nearest to x = 0. Also, the universal value of the scaling parameter α , obtained numerically, is

$$\alpha = 2.502907875 \dots . \tag{36}$$

Like δ , α is a number that can be measured [through an experiment that observes the d_n of Eq. (28)] in any phenomenon exhibiting period doubling.

If g_1 is universal, then of course its iterate g_1^2 also is universal. Figure 7b

depicts an early approximation to this iterate. In fact, let us define a new universal function g_0 , obtained by scaling g_1^2 :

$$g_0(x) \equiv -\alpha g_1^2(-x/\alpha). \tag{37}$$

(Because g_1 is universal and the iterates of our quadratic function are all symmetric in x, both g_1 and g_0 are symmetric functions. Accordingly, the minus sign within g_1^2 can be dropped with impunity.) From Eq. (35), we now can write

$$g_0(x) = \lim_{n \to \infty} (-\alpha)^n f^{2^n} (\lambda_n, x/(-\alpha)^n).$$
 (38)

[We introduced the scaling of Eq. (37) to provide one power of α per period doubling, since each successive iterate of f^{2n}

reduces the scale by α .

In fact, we can generalize Eqs. (35) and (38) to a *family* of universal functions g_r:

$$g_{r}(x) = \lim_{n \to \infty} (-\alpha)^{n} f^{2n}(\lambda_{n+r}, x/(-\alpha)^{n}). \quad (39)$$

To understand this, observe that go locates the cycle elements as the fixed points of go at extrema; go locates the same elements by determining two elements per extremum. Similarly, g, determines 2r elements about each extremum near a fixed point of gr. Since each f2n is always magnified by $(-\alpha)^n$ for each r, the scales of all g, are the same. Indeed, g_r for r > 1 looks like g_1 of Fig. 9, except that each extremum is slightly higher, to accommodate a 2r-cycle. Since each extremum must grow by convergently small amounts to accommodate higher and higher 2^r-cycles, we are led to conclude that

$$g(x) = \lim_{r \to \infty} g_r(x) \tag{40}$$

must exist. By Eq. (39),

$$g(x) = \underset{n \to \infty}{\ell im} (-\alpha)^n f^{2n}(\lambda_{\infty}, x/(-\alpha)^n) \,. \tag{41}$$

Unlike the functions g_r , g(x) is obtained as a limit of f^{2n} 's at a *fixed value* of λ . Indeed, this is the special significance of λ_{∞} ; it is an isolated value of λ at which repeated iteration and magnification lead to a convergent function.

We now can write the equation that g satisfies. Analogously to Eq. (37), it is easy to verify that all g_r are related by

$$g_{r-1}(x) = -\alpha g_r(g_r(-x/\alpha))$$
. (42)

By Eq. (40), it follows that g satisfies

$$g(x) = -\alpha g(g(x/\alpha)). \tag{43}$$

The reader can verify that Eq. (43) is in-

variant under a magnification of g. Thus, the theory has nothing to say about absolute scales. Accordingly, we must fix this by hand by setting

$$g(0) = 1$$
. (44)

Also, we must specify the nature of the maximum of g at x = 0 (for example, quadratic). Finally, since g is to be built by iterating $a - x^2$, it must be both smooth and a function of x through x^2 . With these specifications, Eq. (43) has a unique solution. By Eqs. (44) and (43).

$$g(0) = 1 = -\alpha g(g(0)) = -\alpha g(1)$$
,

so that

$$\alpha = -1/g(1). \tag{45}$$

Accordingly, Eq. (43) determines α together with g.

Let us comment on the nature of Eq. (43), a so-called functional equation. Because g is smooth, if we know its value at a finite number of points, we know its value to some approximation on the interval containing these points by any sufficiently smooth interpolation. Thus, to some degree of accuracy, Eq. (43) can be replaced by a finite coupled system of nonlinear equations. Exactly then, Eq. (43) is an infinite-dimensional, nonlinear vector equation. Accordingly, we have obtained the solution to onedimensional period doubling through our infinite-dimensional, explicitly universal problem. Equation (43) must be infinitedimensional because it must keep track of the infinite number of cycle elements demanded of any attempt to solve the period-doubling problem. Rigorous mathematics for equations like Eq. (43) is just beyond the boundary of present mathematical knowledge.

At this point, we must determine two items. First, where is δ ? Second, how do we obtain g_1 , the real function of interest for locating cycle elements? The two

problems are part of one question. Equation (42) is itself an iteration scheme. However, unlike the elements in Eq. (4), the elements acted on in Eq. (42) are functions. The analogue of the function of f in Eq. (4) is the operation in function space of functional composition followed by a magnification. If we call this operation T, and an element of the function space ψ , Eq. (42) gives

$$T|\psi|(x) = -\alpha \psi^2(-x/\alpha). \tag{46}$$

In terms of T, Eq. (42) now reads

$$g_{r-1} = T[g_r], \qquad (47)$$

and Eq. (43) reads

$$g = T|g|. (48)$$

Thus, g is precisely the fixed point of T. Since g is the limit of the sequence g, we can obtain g, for large r by linearizing T about its fixed point g. Once we have g, in the linear regime, the exact repeated application of T by Eq. (47) will provide g₁. Thus, we must investigate the stability of T at the fixed point g. However, it is obvious that T is unstable at g: for a large enough r, g, is a point arbitrarily close to the fixed point g; by Eq. (47), successive iterates of g_r under T move away from g. How unstable is T? Consider a one-parameter family of functions f₂, which means a "line" in the function space. For each f, there is an isolated parameter value λ_{∞} , for which repeated applications of T lead to convergence towards g [Eq. (41)]. Now, the function space can be "packed" with all the lines corresponding to the various f's. The set of all the points on these lines specified by the respective λ_{∞} 's determines a "surface" having the property that repeated applications of T to any point on it will converge to g. This is the surface of stability of T (the "stable manifold" of T through g). But through each point of this surface issues out the corresponding line, which is onedimensional since it is parametrized by a single parameter, λ . Accordingly, T is *unstable* in only *one* direction in function space. Linearized about g, this line of instability can be written as the one-parameter family

$$f_{\lambda}(x) = g(x) - \lambda h(x)$$
, (49)

which passes through g (at $\lambda = 0$) and deviates from g along the unique direction h. But f_{λ} is just one of our transformations [Eq. (4)]! Thus, as we vary λ , f_{λ} will undergo period doubling, doubling to a 2ⁿ-cycle at \wedge_n . By Eq. (41), λ_{∞} for the family of functions f_{λ} in Eq. (49) is

$$\lambda_{\infty} = 0. ag{50}$$

Thus, by Eq. (1)

$$\lambda_n \sim \delta^{-n}$$
 (51)

Since applications of T by Eq. (47) iterate in the opposite direction (diverge away from g), it now follows that the rate of instability of T along h must be precisely δ .

Accordingly, we find δ and g_1 in the following way. First, we must linearize the operation T about its fixed point g. Next, we must determine the stability directions of the linearized operator. Moreover, we expect there to be precisely one direction of instability. Indeed, it turns out that infinitesimal deformations (conjugacies) of g determine stable directions, while a unique unstable direction, h, emerges with a stability rate (eigenvalue) precisely the δ of Eq. (3). Equation (49) at λ_r is precisely g_r for asymptotically large r. Thus gr is known asymptotically, so that we have entered the sequence g_r and can now, by repeated use of Eq. (47), step down to g₁. All the ingredients of a full description of high-order 2n-cycles now are at hand and evidently are universal.

Although we have said that the function g₁ universally locates cycle elements near x = 0, we must understand that it doesn't locate all cycle elements. This is possible because a finite distance of the scale of g1 (for example, the location of the element nearest to x = 0) has been magnified by α^n for n diverging. Indeed, the distances from x = 0 of all elements of a 2ⁿ-cycle, "accurately" located by g₁, are reduced by $-\alpha$ in the 2^{n+1} -cycle. However, it is obvious that some elements have no such scaling: because f(0) $= a_n$ in Eq. (13), and $a_n \rightarrow a_{\infty}$, which is a definite nonzero number, the distance from the origin of the element of the 2ⁿcycle farthest to the right certainly has not been reduced by $-\alpha$ at each period doubling. This suggests that we must measure locations of elements on the far right with respect to the farthest right point. If we do this, we can see that these distances scale by α^2 , since they are the images through the quadractic maximum of f at x = 0 of elements close to x = 0 scaling with $-\alpha$. In fact, if we image g, through the maximum of f (through a quadratic conjugacy), then we shall indeed obtain a new universal function that locates cycle elements near the right-most element. The correct description of a highly doubled cycle now emerges as one of universal local clusters.

We can state the scope of universality for the location of cycle elements precisely. Since $f(\lambda_1, x)$ exactly locates the two elements of the 21-cycle, and since $f(\lambda_1, x)$ is an approximation to g_1 [n = 0 in Eq. (35), we evidently can locate both points exactly by appropriately sealing g₁. Next, near x = 0, $f^2(\lambda_2, x)$ is a better approximation to g1 (suitably scaled). However, in general, the more accurately we scale g, to determine the smallest 2-cycle elements, the greater is the error in its determination of the rightmost elements. Again, near x = 0, $f^4(\lambda_3,$ x) is a still better approximation to g₁. Indeed, the suitably scaled g, now can determine several points about x = 0 accurately, but determination of the right-

most elements is still worse. In this fashion, it follows that g1, suitably scaled, can determine 2r points of the 2ncycle near x = 0 for $r \ll n$. If we focus on the neighborhood of one of these 2' points at some definite distance from x = 0, then by Eq. (35) the larger the n, the larger the scaled distance of this region from x = 0, and so, the poorer the approximation of the location of fixed points in it by g1. However, just as we can construct the version of g1 that applies at the right-most cycle element, we also can construct the version of g, that applies at this chosen neighborhood. Accordingly, the universal description is set through an acceptable tolerance: if we "measure" f2n at some definite n, then we can use the actual location of the elements as foci for 2ⁿ versions of g₁, each applicable at one such point. For all further period doubling, we determine the new cycle elements through the g₁'s. In summary, the more accurately we care to know the locations of arbitrarily high-order cycle elements, the more parameters we must measure (namely. the cycle elements at some chosen order of period doubling). This is the sense in which the universality theory is asymptotic. Its ability to have serious predictive power is the fortunate consequence of the high convergence rate $\delta(\sim 4.67)$. Thus, typically after the first two or three period doublings, this asymptotic theory is already accurate to within several percent. If a perioddoubling system is measured in its 4- or 8-cycle, its behavior throughout and symmetrically beyond the perioddoubling regime also is determined to within a few percent.

To make precise dynamical predictions, we do not have to construct all the local versions of g_1 ; all we really need to know is the local *scaling* everywhere along the attractor. The scaling is $-\alpha$ at x = 0 and α^2 at the right-most element. But what is it at an arbitrary point? We can determine the scaling law if we order

elements not by their location on the x-axis, but rather by their order as iterates of x = 0. Because the time sequence in which a process evolves is precisely this ordering, the result will be of immediate and powerful predictive value. It is precisely this scaling law that allows us to compute the spectrum of the onset of turbulence in period-doubling systems.

What must we compute? First, just as the element in the 2^n -cycle nearest to x=0 is the element halfway around the cycle from x=0, the element nearest to an arbitrarily chosen element is precisely the one halfway around the cycle from it. Let us denote by $d_n(m)$ the distance between the m^{th} cycle element (x_m) and the element nearest to it in a 2^n -cycle. [The d_n of Eq. (28) is $d_n(0)$]. As just explained,

$$d_n(m) = x_m - f^{2n-1}(\lambda_n, x_m).$$
 (52)

However, x_m is the mth iterate of $x_0 = 0$. Recalling from Eq. (6) that powers commute, we find

$$d_{n}(m) = f^{m}(\lambda_{n}, 0) - f^{m}(\lambda_{n}, f^{2n-1}(\lambda_{n}, 0)).$$
 (53)

Let us, for the moment, specialize to m of the form 2^{n-r} , in which case

$$\begin{split} d_{n}(2^{n-r}) &= f^{2^{n-r}}(\lambda_{n}.0) \\ &- f^{2^{n-r}}(\lambda_{n}.f^{2^{n-1}}(\lambda_{n}.0)) \\ &= f^{2^{n-r}}(\lambda_{(n-r)+r}.0) \\ &- f^{2^{n-r}}(\lambda_{(n-r)+r}.f^{2^{n-1}}(\lambda_{n}.0)) \;. \end{split}$$

For $r \ll n$ (which can still allow $r \gg 1$ for n large), we have, by Eq. (39),

$$\begin{split} d_{n}(2^{n-r}) \, \sim \, (-\alpha)^{-(n-r)} \big| \, g_{r}(0) \\ &- \, g_{r}((-\alpha)^{n-r} \, \, f^{2^{n-1}}(\lambda_{n},\! 0)) \big| \end{split}$$

or

$$d_{n}(2^{n-r}) \sim (-\alpha)^{-(n-r)} |g_{r}(0)| - g_{r}((-\alpha)^{-r+1} g_{1}(0))|.$$
 (55)

The object we want to determine is the local scaling at the m^{th} element, that is, the ratio of nearest separations at the m^{th} iterate of x = 0, at successive values of n. That is, if the scaling is called σ ,

$$\sigma_{n}(m) \equiv \frac{d_{n+1}(m)}{d_{n}(m)} \quad . \tag{56}$$

|Observe by Eq. (28), the definition of α , that $\sigma_n(0) \sim (-\alpha)^{-1}$.| Specializing again to $m=2^{n-r}$, where $r\ll n$, we have by Eq. (55)

$$\sigma(2^{n-r}) \sim \frac{g_{r+1}(0) - g_{r+1}((-\alpha)^{-r}g_1(0))}{g_r(0) - g_r((-\alpha)^{-r+1}g_1(0))} \quad . \eqno(57)$$

Finally, let us rescale the axis of iterates so that all 2^{n+1} iterates are within a unit interval. Labelling this axis by t, the value of t of the mth element in a 2^n -cycle is

$$t_n(m) = m/2^n. (58)$$

In particular, we have

$$t_n(2^{n-r}) = 2^{-r}$$
. (59)

Defining σ along the t-axis naturally as

$$\sigma(t_n(m)) \sim \sigma_n(m)$$
 (as $n \to \infty$).

we have by Eqs. (57) and (59),

$$\sigma(2^{-r-1}) \ = \frac{g_{r+1}(0) \ - \ g_{r+1}((-\alpha)^{-r}g_1(0))}{g_r(0) \ - \ g_r((-\alpha)^{-r+1}g_1(0))} \ . \eqno(60)$$

It is not much more difficult to obtain σ for all t. This is done first for rational t by writing t in its binary expansion:

(55)
$$t_{r_1r_2r_3...} = 2^{-r_1} + 2^{-r_2} + ...$$

In the 2^n -cycle approximation we require σ_n at the $2^{n-r_1} + 2^{n-r_2} + ...$ iterate of the origin. But, by Eq. (8),

$$f^{2^{n-r_1}} + {}^{2^{n-r_2}} + \cdots = f^{2^{n-r_1}} \circ \ f^{2^{n-r_2}} \circ \ \dots .$$

It follows by manipulations identical to those that led from Eq. (54) to Eq. (60) that σ at such values of t is obtained by replacing the individual g_r terms in Eq. (60) by appropriate iterates of various g_r 's.

There is one last ingredient to the computation of σ . We know that $\sigma(0) = -\alpha^{-1}$. We also know that $\sigma_n(1) \sim \alpha^{-2}$. But, by Eq. (59),

$$t_n(1) = 2^{-n} \to 0$$
.

Thus σ is discontinuous at t=0, with $\sigma(0-\epsilon)=-\alpha^{-1}$ and $\sigma(0+\epsilon)=\alpha^{-2}(\epsilon\to 0^+).$ Indeed, since $x_{2^{n-r}}$ is always very close to the origin, each of these points is imaged quadratically. Thus Eq. (60) actually determines $\sigma(2^{-r-1}-\epsilon)$, while $\sigma(2^{-r-1}+\epsilon)$ is obtained by replacing each numerator and denominator g_r by its square. The same replacement also is correct for each multi- g_r term that figures into σ at the binary expanded rationals.

Altogether, we have the following results. $\sigma(t)$ can be computed for all t, and it is universal since its explicit computation depends only upon the universal functions g_r. σ is discontinuous at all the rationals. However, it can be established that the larger the number of terms in the binary expansion of a rational t, the smaller the discontinuity of o. Lastly, as a finite number of iterates leaves t unchanged as $n \to \infty$, σ must be continuous except at the rationals. Figure 10 depicts $1/\sigma(t)$. Despite the pathological nature of σ, the reader will observe that basically it is constant half the time at α^{-1} and half the time at α^{-2} for $0 < t < \frac{1}{2}$. In a succeeding approximation, it can be decomposed in each half into two slightly different quarters,

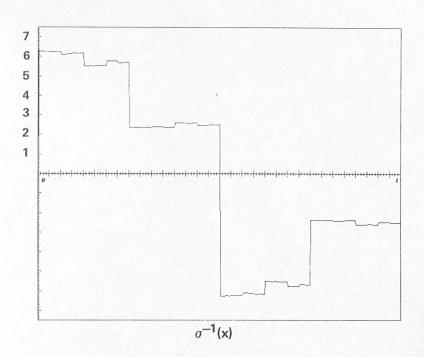


Fig. 10. The trajectory scaling function. Observe that $\sigma(x + 1/2) = -\sigma(x)$.

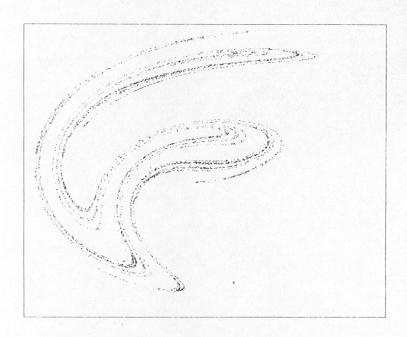


Fig. 11. The plotted points lie on the "strange attractor" of Duffing's equation.

and so forth. [It is easy to verify from Eq. (52) that σ is periodic in t of period 1, and has the symmetry

$$\sigma(t + \frac{1}{2}) = -\sigma(t) .$$

Accordingly, we have paid attention to its first half $0 < t < \frac{1}{2}$. With σ we are at last finished with one-dimensional iterates per se.

Universal Behavior in Higher Dimensional Systems

So far we have discussed iteration in *one* variable; Eq. (15) is the prototype. Equation (14), an example of iteration in two dimensions, has the special property of preserving areas. A generalization of Eq. (14),

$$\mathbf{x}_{\mathsf{n}+1} = \mathbf{y}_{\mathsf{n}} - \mathbf{x}_{\mathsf{n}}^2$$

and

$$y_{n+1} = a + bx_n \tag{61}$$

with |b| < 1, contracts areas. Equation (61) is interesting because it possesses a so-called strange attractor. This means an attractor (as before) constructed by folding a curve repeatedly upon itself (Fig. 11) with the consequent property that two initial points very near to one another are, in fact, very far from each other when the distance is measured along the folded attractor, which is the path they follow upon iteration. This means that after some iteration, they will soon be far apart in actual distance as well as when measured along the attractor. This general mechanism gives a system highly sensitive dependence upon its initial conditions and a truly statistical character: since very small differences in initial conditions are magnified quickly, unless the initial conditions are known to infinite precision, all known knowledge is eroded rapidly to future ignorance. Now, Eq. (61) enters

into the early stages of statistical behavior through period doubling. Moreover, δ of Eq. (3) is again the rate of onset of complexity, and α of Eq. (31) is again the rate at which the spacing of adjacent attractor points is vanishing. Indeed, the one-dimensional theory determines all behavior of Eq. (61) in the onset regime.

In fact, dimensionality is irrelevant. The same theory, the same numbers, etc. also work for iterations in N dimensions, provided that the system goes through period doubling. The basic process, wherever period doubling occurs ad infinitum, is functional composition from one level to the next. Accordingly, a modification of Eq. (29) is at the heart of the process, with composition on functions from N dimensions to N dimensions. Should the specific iteration function contract N-dimensional volumes (a dissipative process), then in general there is one direction of slowest contraction, so that after a number of iterations the process is effectively one-dimensional. Put differently, the one-dimensional solution to Eq. (29) is always a solution to its N-dimensional analogue. It is the relevant fixed point of the analogue if the iteration function is contractive.

Universal Behavior in Differential Systems

The next step of generalization is to include systems of differential equations. A prototypic equation is Duffing's oscillator, a driven damped anharmonic oscillator,

$$\ddot{x} + k\dot{x} + x^3 = b\sin 2\pi t$$
. (62)

The periodic drive of period 1 determines a natural time step. Figure 12a depicts a period 1 attractor, usually referred to as a *limit cycle*. It is an attractor because, for a range of initial conditions, the solution to Eq. (62) settles down to the cycle. It is period 1 because it repeats the same curve in every period of the drive.

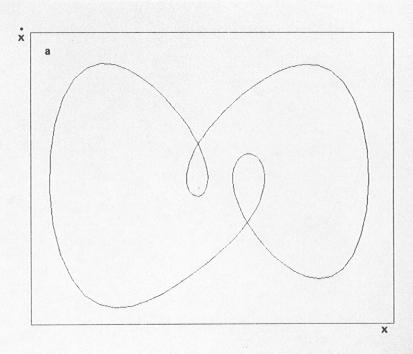


Fig. 12a. The most stable 1-cycle of Duffing's equation in phase space (x,\dot{x}) .

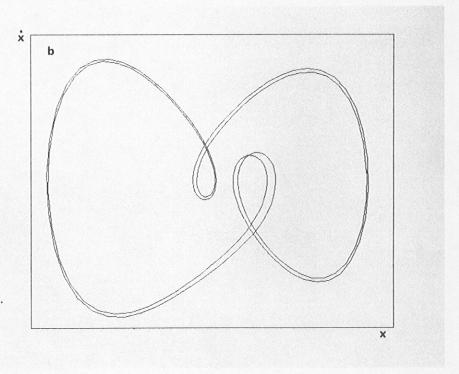


Fig. 12b. The most stable 2-cycle of Duffing's equation. Observe that it is two displaced copies of Fig. 12a.

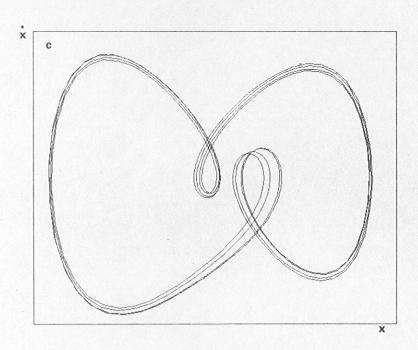


Fig. 12c. The most stable 4-cycle of Duffing's equation. Observe that the displaced copies of Fig. 12b have either a broad or a narrow separation.

Figures 12b and c depict attractors of periods 2 and 4 as the friction or damping constant k in Eq. (62) is reduced systematically. The parameter values k $= \lambda_0, \lambda_1, \lambda_2, ...,$ are the damping constants corresponding to the most stable 2^{n} -cycle in analogy to the λ_{n} of the onedimensional functional iteration. Indeed, this oscillator's period doubles (at least numerically!) ad infinitum. In fact, by k = λ_5 , the δ_3 of Eq. (2) has converged to 4.69. Why is this? Instead of considering the entire trajectories as shown in Fig. 12, let us consider only where the trajectory point is located every 1 period of the drive. The 1-cycle then produces only one point, while the 2-cycle produces a pair of points, and so forth. This time-one map [if the trajectory point is (x,\dot{x}) now, where is it one period later? is by virtue of the differential equation a smooth and invertible func-

tion in two dimensions. Qualitatively, it looks like the map of Eq. (61). In the present state of mathematics, little can be said about the analytic behavior of time-one maps; however, since our theory is universal, it makes no difference that we don't know the explicit form. We still can determine the complete quantitative behavior of Eq. (62) in the onset regime where the motion tends to aperiodicity. If we already know, by measurement, the precise form of the trajectory after a few period doublings, we can compute the form of the trajectory as the friction is reduced throughout the region of onset of complexity by carefully using the full power of the universality theory to determine the spacings of elements of a cycle.

Let us see how this works in some detail. Consider the time-one map of the

Duffing's oscillator in the superstable 2ⁿcycle. In particular, let us focus on an element at which the scaling function o (Fig. 10) has the value σ_0 , and for which the next iterate of this element also has the scaling σ_0 . (The element is not at a big discontinuity of σ .) It is then intuitive that if we had taken our time-one examination of the trajectory at values of time displaced from our first choice, we would have seen the same scaling σ_0 for this part of the trajectory. That is, the differential equations will extend the map-scaling function continuously to a function along the entire trajectory so that, if two successive time-one elements have scaling σ_0 , then the entire stretch of trajectory over this unit time interval has scaling σ_0 . In the last section, we were motivated to construct σ as a function of t along an interval precisely towards this end.

To implement this idea, the first step is to define the analogue of d_n . We require the spacing between the trajectory at time t and at time $T_n/2$ where the period of the system in the 2^n -cycle is

$$T_n \cong 2^n T_0. \tag{63}$$

That is, we define

$$d_n(t) \equiv x_n(t) - x_n(t + T_n/2)$$
. (64)

(There is a d for each of the N variables for a system of N differential equations.) Since σ was defined as periodic of period 1, we now have

$$d_{n+1}(t) \sim \sigma(t/T_{n+1})d_n(t)$$
. (65)

The content of Eq. (65), based on the n-dependence arising solely through the T_n in σ , and not on the detailed form of σ , already implies a strong scaling prediction, in that the ratio

$$\frac{d_{n+1}(t)}{d_n(t)} \ ,$$

when plotted with t scaled so that $T_n =$

1, is a function independent of n. Thus if Eq. (65) is true for some σ , whatever it might be, then knowing $x_n(t)$, we can compute $d_n(t)$ and from Eq. (65) $d_{n+1}(t)$. As a consequence of periodicity, Eq. (64) for $n \rightarrow n + 1$ can be solved for $x_{n+1}(t)$ (through a Fourier transform). That is, if we have measured any chosen coordinate of the system in its 2ⁿ-cycle, we can compute its time dependence in the 2ⁿ⁺¹-cycle. Because this procedure is recursive, we can compute the coordinate's evolution for all higher cycles through the infinite period-doubling limit. If Eq. (65) is true and σ not known, then by measurement at a 2ⁿ-cycle and at a 2^{n+1} -cycle, σ could be constructed from Eq. (65), and hence all higher order doublings would again be determined. Accordingly, Eq. (65) is a very powerful result. However, we know much more. The universality theory tells us that period doubling is universal and that there is a unique function o which, indeed, we have computed in the previous section. Accordingly, by measuring x(t) in some chosen 2ⁿ-cycle (the higher the n, the more the number of effective parameters to be determined empirically, and the more precise are the predictions), we now can compute the entire evolution of the system on its route to turbulence.

How well does this work? The empirically determined σ [for Eq. (62)] of Eq. (65) is shown for n = 3 in Fig. 13a and n = 4 in Fig. 13b. The figures were constructed by plotting the ratios of d_{n+1} and d_n scaled respective to T = 16 in Fig. 13a and T = 32 in Fig. 13b. Evidently the scaling law Eq. (65) is being obeyed. Moreover, on the same graph Fig. 14 shows the empirical σ for n = 4 and the recursion theoretical σ of Fig. 10. The reader should observe the detail-by-detail agreement of the two. In fact, if we use Eq. (65) and the theoretical σ with n = 2 as empirical input, the n = 5 frequency spectrum agrees with the empirical n = 5 spectrum to

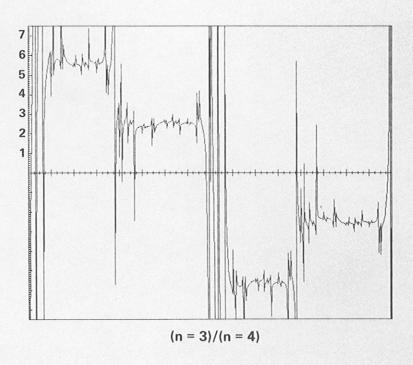


Fig. 13a. The ratio of nearest copy separations in the 8-cycle and 16-cycle for Duffing's equation.

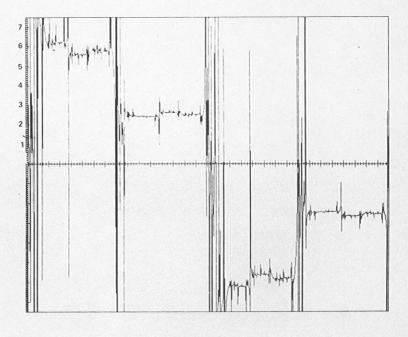


Fig. 13b. The same quantity as in Fig. 13a, but for the 16-cycle and 32-cycle. Here, the time axis is twice as compressed.

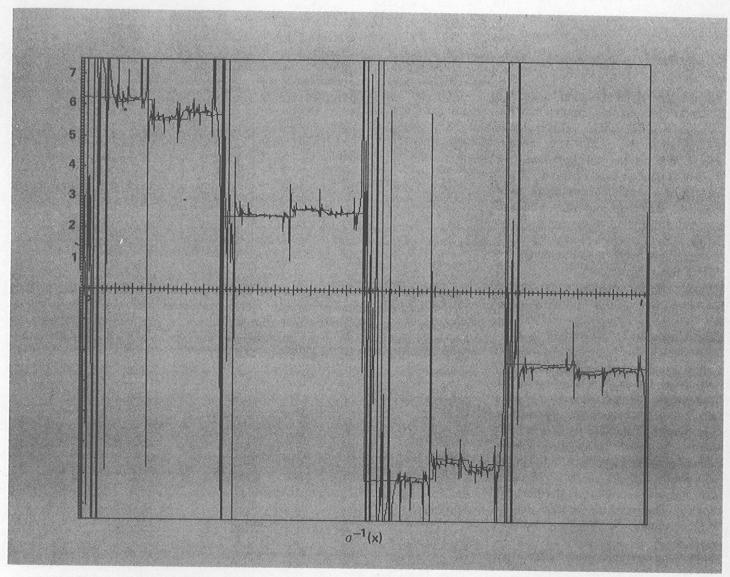


Fig. 14. Figure 13b overlayed with Fig. 10 compares the universal scaling function σ with the empirically determined scaling of nearest copy separations from the 16-cycle to the 32-cycle for Duffing's equation.

within 10%. (The n=4 determines n=5 to within 1%.) Thus the asymptotic universality theory is correct *and* is already well obeyed, even by n=2!

Equations (64) and (65) are solved, as mentioned above, through Fourier transforming. The result is a recursive scheme that determines the Fourier coefficients of $x_{n+1}(t)$ in terms of those of $x_n(t)$ and the Fourier transform of the (known) function $\sigma(t)$. To employ the formula accurately requires knowledge of the entire spectrum of x_n (amplitude and phase) to determine each coefficient of x_{n+1} . However, the formula enjoys an

approximate local prediction, which roughly determines the amplitude of a coefficient of x_{n+1} in terms of the amplitudes (alone) of x_n near the desired frequency of x_{n+1} .

What does the spectrum of a period-doubling system look like? Each time the period doubles, the fundamental frequency halves; period doubling in the continuum version is termed half-subharmonic bifurcation, a typical behavior of coupled nonlinear differential equations. Since the motion almost reproduces itself every period of the drive, the amplitude at this original fre-

quency is high. At the first subharmonic halving, spectral components of the odd halves of the drive frequency come in. On the route to aperiodicity they saturate at a certain amplitude. Since the motion more nearly reproduces itself every two periods of drive, the next saturated subharmonics, at the odd fourths of the original frequency, are smaller still than the first ones, and so on, as each set of odd 2ⁿths comes into being. A crude approximate prediction of the theory is that whatever the system, the saturated amplitudes of each set of successively lower half-frequencies

define a smooth interpolation located 8.2 dB below the smooth interpolation of the previous half-frequencies. [This is shown in Fig. 15 for Eq. (62).] After subharmonic bifurcations ad infinitum, the system is now no longer periodic; it has developed a continuous broad spectrum down to zero frequency with a definite internal distribution of the energy. That is, the system emerges from this process having developed the beginnings of broad-band noise of a determined nature. This process also occurs in the onset of turbulence in a fluid.

The Onset of Turbulence

The existing idea of the route to turbulence is Landau's 1941 theory. The idea is that a system becomes turbulent through a succession of instabilities, where each instability creates a new degree of freedom (through an indeterminate phase) of a time-periodic nature with the frequencies successively higher and incommensurate (not harmonics); because the resulting motion is the superposition of these modes, it is quasiperiodic.

In fact, it is experimentally clear that quasi-periodicity is incorrect. Rather, to produce the observed noise of rapidly decaying correlation the spectrum must become continuous (broad-band noise) down to zero frequency. The defect can be eliminated through the production of successive half-subharmonics, which then emerge as an allowable route to turbulence. If the general idea of a succession of instabilities is maintained, the new modes do not have indeterminate phases. However, only a small number of modes need be excited to produce the required spectrum. (The number of modes participating in the transition is, as of now, an open experimental question.) Indeed, knowledge of the phases of a small number of amplitudes at an early stage of period doubling suffices to determine the phases of the transition

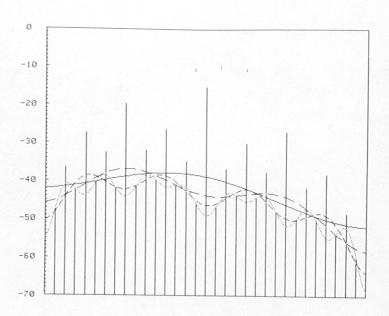


Fig. 15. The subharmonic spectrum of Duffing's equation in the 32-cycle. The dotted curve is an interpolation of the odd 32nd subharmonics. The shorter dashed curve is constructed similarly for the odd 16th subharmonics, but lowered by 8.2 dB. The longer dashed curve of the 8th subharmonics has been dropped by 16.4 dB, and the solid curve of the 4th subharmonics by 24.6 dB.

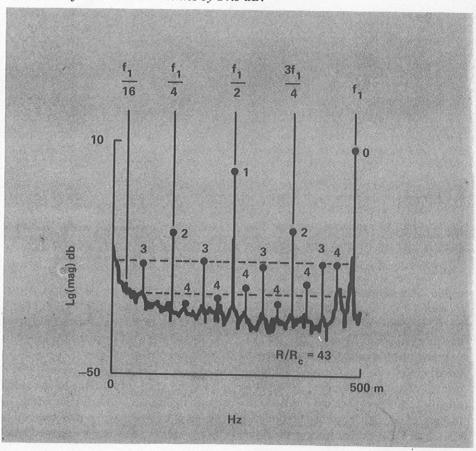


Fig. 16. The experimental spectrum (redrawn from Libchaber and Maurer) of a convecting fluid at its transition to turbulence. The dashed lines result from dropping a horizontal line down through the odd 4th subharmonics (labelled 2) by 8.2 and 16.4 dB.



Mitchell J. Feigenbaum is a mathematical physicist and inventor of the universality theory. He earned his bachelor of electrical engineering degree from the City College of New York in 1964 and his Ph.D. in elementary particle physics from Massachusetts Institute of Technology in 1970. He was a Research Associate at Cornell University and Virginia Polytechnic Institute before becoming a Staff Member in the Theoretical Division at LASL in 1974. In May, 1980, he received a LASL Distinguished Performance Award for his universality theory and development of the first quantitative understanding of the onset of turbulence. He is presently writing a monograph on this work for the series Progress in Physics published by Birkhauser Boston, Inc. His other technical interests include field theories and functional integrals, the renormalization group and phase transitions, and nonlinear dynamics generally. His peers at LASL often turn to him as the resident consultant on related technical matters.

spectrum. What is important is that a purely causal system can and does possess essentially statistical properties. Invoking *ad hoc* statistics is unnecessary and generally incompatible with the true dynamics.

A full theoretical computation of the onset demands the calculation of successive instabilities. The method used traditionally is perturbative. We start at the static solution and add a small timedependent piece. The fluid equations are linearized about the static solution, and the stability of the perturbation is studied. To date, only the first instability has been computed analytically. Once we know the parameter value (for example, the Rayleigh number) for the onset of this first time-varying instability, we must determine the correct form of the solution after the perturbation has grown large beyond the linear regime. To this solution we add a new time-dependent perturbative mode, again linearized (now about a time-varying, nonanalytically available solution) to discover the new instability. To date, the second step of the analysis has been performed only numerically. This process, in principle, can be repeated again and again until a suitably turbulent flow has been obtained. At each successive stage, the computation grows successively more intractable.

However, it is just at this point that the universality theory solves the problem; it works only after enough instabilities have entered to reach the asymptotic regime. Since just two such instabilities already serve as a good approximate starting point, we need only a few parameters for each flow to empower the theory to complete the hard part of the infinite cascade of more complex instabilities.

Why should the theory apply? The fluid equations make up a set of coupled field equations. They can be spatially Fourier-decomposed to an infinite set of coupled ordinary differential equations. Since a flow is viscous, there is some smallest spatial scale below which no significant excitation exists. Thus, the equations are effectively a finite coupled set of nonlinear differential equations. The number of equations in the set is completely irrelevant. The universality theory is generic for such a dissipative system of equations. Thus it is possible that the flow exhibits period doubling. If it does, then our theory applies. However, to prove that a given flow (or any flow) actually should exhibit doubling is well beyond present understanding. All we can do is experiment.

Figure 16 depicts the experimentally measured spectrum of a convecting liquid helium cell at the onset of turbulence. The system displays measurable period doubling through four or five levels; the spectral components at each set of odd half-subharmonics are labelled with the level. With n = 2 taken as

asymptotic, the dotted lines show the crudest interpolations implied for the n=3, n=4 component. Given the small amount of *amplitude* data, the interpolations are perforce poor, while ignorance of higher odd multiples prevents construction of any significant interpolation at the right-hand side. Accordingly, to do the crudest test, the farthest right-hand amplitude was dropped, and the oscillations were smoothed away by averaging. The experimental results, -8.3 dB and -8.4 dB, are in surprisingly good agreement with the theoretical 8.2!

From this good experimental agreement and the many period doublings as the clincher, we can be confident that the measured flow has made its transition according to our theory. A measurement of δ from its fundamental definition would, of course, be altogether convincing. (Experimental resolution is insufficient at present.) However, if we work backwards, we find that the several percent agreement in 8.2 dB is an experimental observation of a in the system to the same accuracy. Thus, the present method has provided a theoretical calculation of the actual dynamics in a field where such a feat has been impossible since the construction of the Navier-Stokes equations. In fact, the scaling law Eq. (65) transcends these equations, and applies to the true equations, whatever they may be.