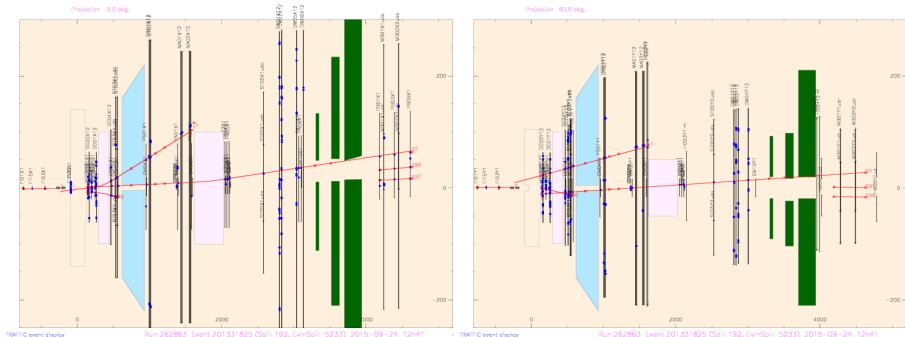


Detector Alignment

September 24, 2015

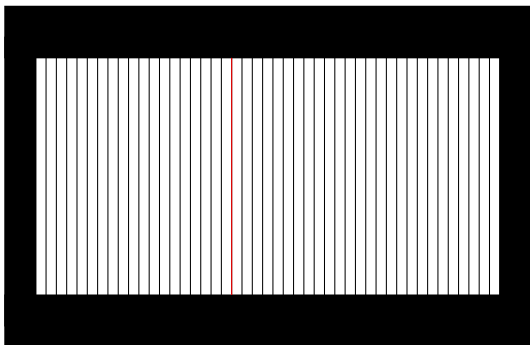
Introduction

You have seen an event display with some tracks reconstructed...



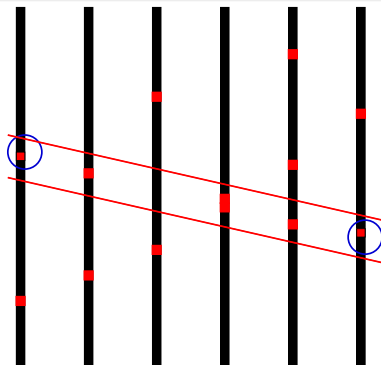
But how to make track?!

The Simplest Detector



- Passing charged particle will 'fire a wire'
- There is also a noise and a wire can be fired randomly with some probability
- Basically, based on the wire numbers at different position along the beam line one must decide if the track can be build...

Tracking...



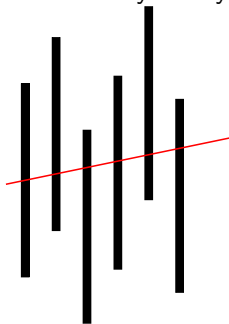
- Select 'pivot points', select route, add hits to a track...
- Sounds simple, but:
 - usually 10x hits than on the figure
 - tracks are not necessary straight lines (magnetic field)
 - one needs to bridge tracks segments through the magnet
 - detectors are not **aligned perfectly** ...

Detector Alignment

- Detector size 5m×3m
- Detector weight 400kg
- You have to hang it: 1.5m above the ground 20m in the N direction away from edge of the white board.
- Question: How precisely can you do it?!

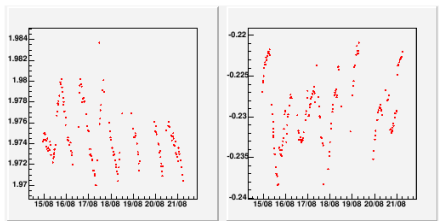
Detector Alignment cont.

- More often than not, detectors are misalignment by 1-2mm
- Best COMPASS detectors have resolution of $5\mu m$.
- If such detector is shifted by 1mm, it means that for a given track instead of signal in a wire 97-103 one of 297-303 will fire!
- In such condition there is no chance to assign correct hit to a track!
- Mechanically it would be extremely costly to improve the situation...



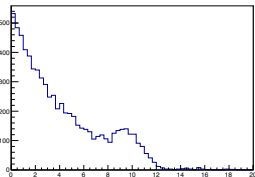
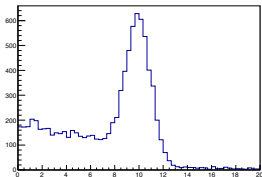
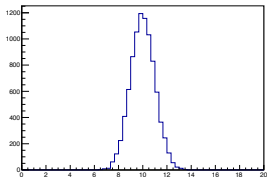
Thermal Expansion...

- Suppose that you somehow managed to put your detector withing a few μm from the desired place...
- Aluminum is relatively 'low cost' and 'low weight' material,
- Detector frames are often build from aluminum
- Its thermal expansion coefficient is $2.3 \cdot 10^{-5}$ 1/K
- There is about 10 degree difference between day and night
- **A 5m long detector can shrink more than a 1 mm!**
- Basically one is almost at the starting point...
- As a results alignment is done software-wise
- Sometimes a new alignment is needed every 30min-1h



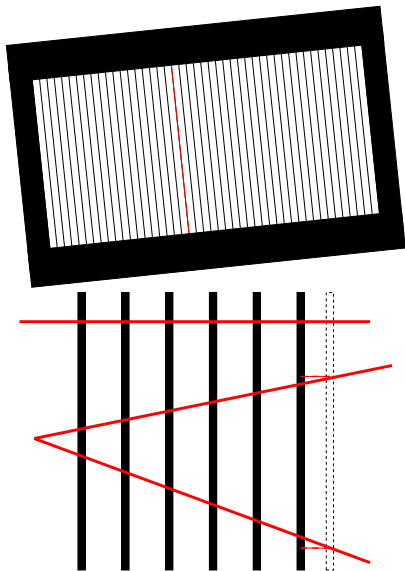
The Simplest Method...

- Low intensity run - one track in the spectrometer
- Two detectors are assumed as pivot points (they will not move)
- Hits in these detectors are used to make a track
- For any other detector one checks the distance is measured between the expected track position and the closest fired wire
- Some spectra for detector miss-aligned by 10 wires and having 0%, 3%, and 10% of a noise



- The method is simple, but:
- Detector may not only be miss-aligned in only one coordinate
 - can be shifted perpendicularly to the wires
 - can be rotated by any of the 3 projections (only 1 rotation is really important)
 - can be shifted along the beam
 - or distance between the wires is different than it is expected

Possible Miss-alignments



How the True Alignment Is Done...

- One tries to simultaneously fit x,y,z rotation and pitch of the detectors.
- To have analytical solution problem has to be linearized e.g. $\sin(\theta) \approx \theta$
- One builds set of equations to compare model with real measurement
$$x_1 + \Delta x_1 + y_1 \Delta \theta_1 + \dots - A_1 z - B_1 = u_{11}$$
$$x_2 + \Delta x_2 + y_2 \Delta \theta_2 + \dots - A_1 z - B_1 = u_{21} .$$

.

.

$$x_n + \Delta x_n + y_n \Delta \theta_n + \dots - A_1 z - B_1 = u_{n1}$$
$$x_1 + \Delta x_1 + y_1 \Delta \theta_1 + \dots - A_2 z - B_2 = u_{12} .$$

.

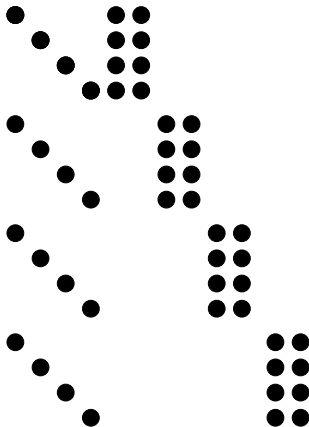
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$$x_n + \Delta x_n + y_n \Delta \theta_n + \dots - A_m z - B_m = u_{nm}$$
- This linear algebra problem has an analytical solution.
- There is only one small detail...

- To solve a linear equation system certain matrix has to be inverted
- We have 300 detectors planes and want align 5 parameters and we use 100000 tracks...
- The matrix we should invert can easily have a few million rows
- In general the matrix inversion is $O(N^3)$ process, and this means that the matrix inversion on normal PC would take a few weeks...
- BTW. There are faster algorithms to invert matrices...

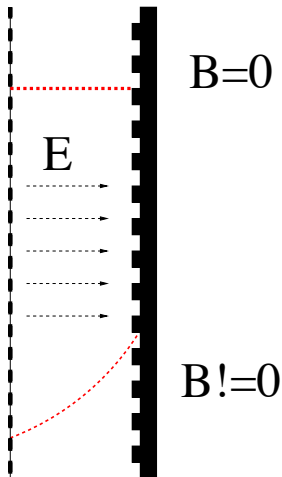
Mathematical Trick...

- The matrix has a special structure
- V. Blobel has shown how to invert it much faster
- In reality only matrix of the size $(300 \times 5) \times (300 \times 5)$ and 100000 (2×2) matrices has to be inverted. This take a few seconds.



You Think You Are Done...

- ... and then you switch on magnetic field...
- Different detectors types behave differently in the magnetic field...



- Gain due to presented alignment method vs. the simplest one

	OLD	NEW	RATIO
tracks/events	1.71	3.09	1.8
χ^2/ndf	8.0	3.1	2.6
Interaction vertex (%)	36%	45%	1.25
μ, μ' (%)	14	33	2.3